

investigate even longer periods of fluctuations.) Figs. 4 and 5 show, as example, the coherence between currents off Cape Upstart and Green Island and between sea level at Townsville and Carter Reef (about 1 year of data). The sea level and current fluctuations were propagating longshore northward at speeds $\approx 450 \text{ km day}^{-1}$, independent of the period.

A term balance analysis was carried out of the f-plane shallow water wave equations, to show that over the shelf, the equations of motion for wind-driven currents reduce to

$$-fv = -gh_x - F^X/H \quad (1)$$

$$v_t + fu = -gh_y + T^Y/H - F^Y/H \quad (2)$$

$$(Hu)_x + (Hv)_y = 0 \quad (3)$$

where t is the time, x and y the horizontal cartesian coordinates (x is cross-shelf pointing offshore, y longshore northward), u and v the velocity components, F^X and F^Y the bottom friction components and T^Y the wind stress. A subscript indicates a partial derivate, g the acceleration due to gravity, H the undisturbed water depth, h the sea level disturbance, f the Coriolis parameter. Taking

$$(F^X, F^Y) = r(u, v) \quad (4)$$

where r is a friction parameter, and, for the forcing,

$$T^Y = (0, y < 0; T_0 \exp(i\omega t), 0 < y < A; 0, y > A) \quad (5)$$

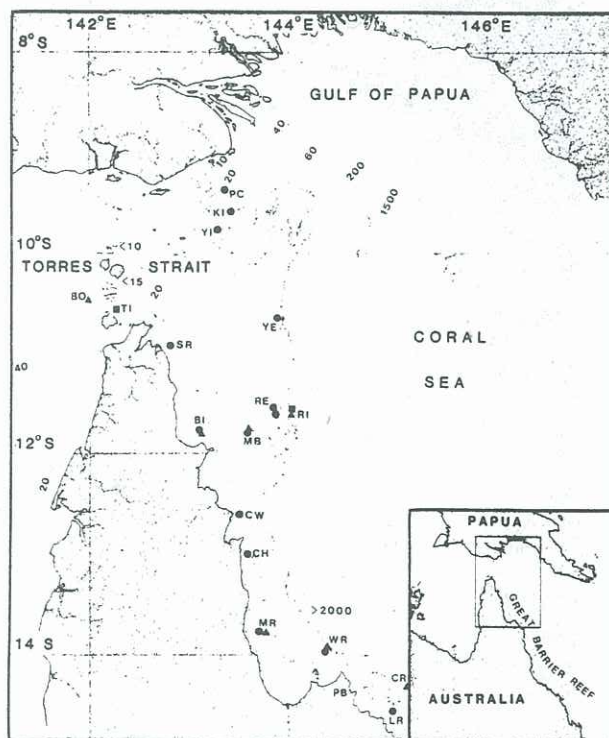


Fig. 2: Map of the northern region of the GBR. (●) current meters, (■) weather station, (▲) tide gauges.

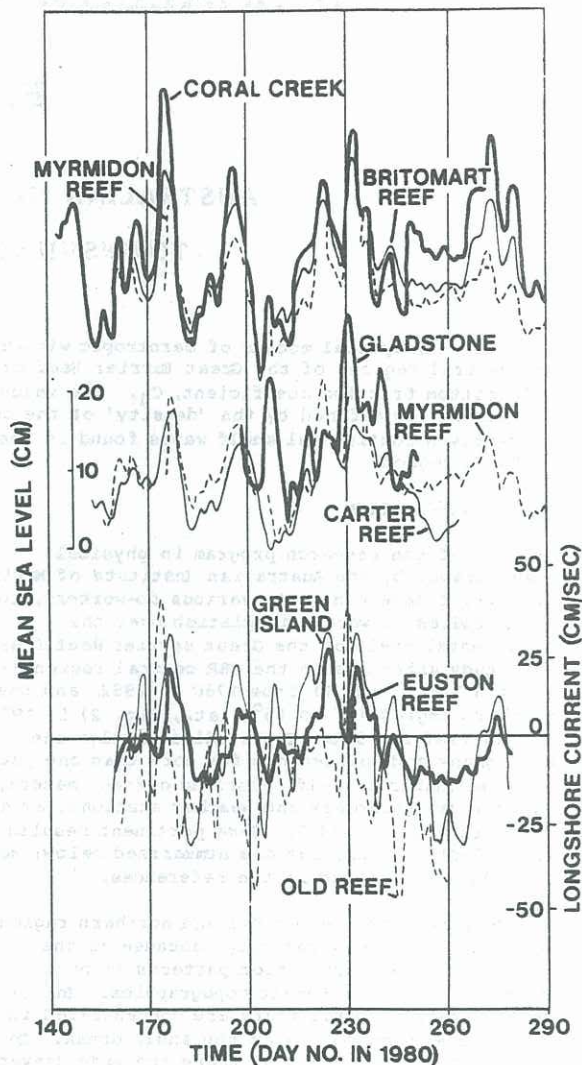


Fig. 3: Typical time series of low-frequency sea level and longshore currents.

where ω is the frequency, A the size of the wind-field, T_0 a constant, $i = (-1)^{1/2}$. For a shelf of width L and constant depth $H_s \ll H_0$, where H_0 is the ocean depth, assuming continuity of h and uH at $x = L$, and $h \rightarrow 0$ as $x \rightarrow \infty$, the solution is

$$u = -x v_y \quad (6)$$

$$h = (x - L) f v / g \quad (7)$$

$$v = B \exp(i\omega t) (1 - \exp(-i\omega y / c)) \exp(-by/c) \quad (8)$$

where $B = (T_0 / H_s) / (i(\omega - ib))$, $b = r / H_s$, $c = -fL$. This simple model produces results that agree well with a number of observations (see slides). The observed overall decay of a shelf wave amplitude as it travels northward is best modelled for $r \approx 2 \times 10^{-4} \text{ m s}^{-1}$, or, assuming

$$(F^X, F^Y) = C_d |u^*| (u, v) \quad (9)$$

where u^* is the root-mean-square velocity (comprising both high and low frequency motions),

$$C_d \approx 0.002 \quad (10)$$

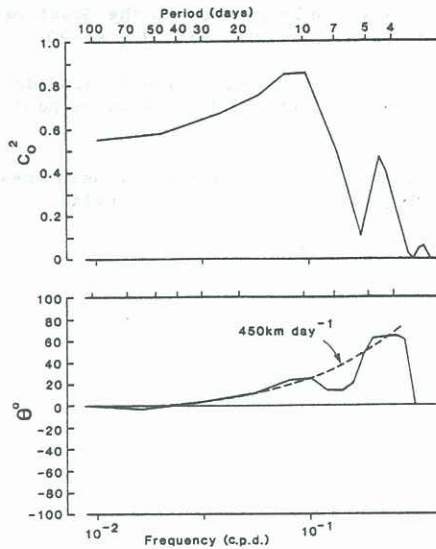


Fig. 4: Square coherence (C_0^2) and phase (θ) between low-frequency longshore currents off Cape Upstart and Green Island (≈ 1 year of data). 95% confidence level for $C_0^2 \approx 0.4$, at 10 day period.

3 THE NORTHERN REGION

The value of C_d was determined separately from the low-frequency wind-driven and the tidal currents. As is shown in the slides, the semi-diurnal tides dominate the tidal signal. Along the shelf break, the longshore gradient of amplitude and phase of the tidal constituents is very small, and, except in reef passages, tidal currents are small. Near the coast, the longshore tidal currents are strong and strong longshore gradients of phase and amplitude are observed, clearly related to the increase in shelf width with latitude, mostly, between 12 and 10°S. These properties can be modelled as follows.

Using a shelf-averaged bottom friction law, the equations of motion are (Battisti and Clarke, 1982)

$$u_t - fv = -gh_x - \lambda_0 u \quad (11)$$

$$v_t + fu = -gh_y - \lambda_0 v \quad (12)$$

$$h_t + (Hu)_x + (Hv)_y = 0 \quad (13)$$

where $\lambda_0 = r/H$ is assumed constant. Taking

$$(u, v, h) = (u_0(x, y), v_0(x, y), h_0(x, y)) \exp(i\omega t) \quad (14)$$

assuming that ℓ is a constant, where

$$i\ell = h_y/h \quad (15)$$

and that $h_{yy} \ll h_{xx}$, it is possible to find a solution in terms of zero order Bessel functions of x . To reproduce in the model the cross-shelf amplification of the M_2 tide, or the M_2 longshore coastal current (see slides), best fit techniques yield $\lambda_0 \approx 3 \times 10^{-4} \text{ s}^{-1}$, or roughly,

$$C_d \approx 0.01-0.03 \quad (16)$$

The second estimate of C_D is derived from an analysis of the term balance in the equations of motion for wind-driven currents. This time, contrary to the situation in the central region, the term v_t is negligible in the longshore momentum eq. (2). Travelling waves thus cannot exist, and indeed are not observed (see slides), and only quasi-steady arrested topographic waves are present (e.g. Csanady, 1978). 'Upstream' and 'downstream' boundary conditions are needed to solve the equations. The model based on eqs. (1) to (3), neglecting v_t , yields a favourable comparison between observed and computed currents (Fig. 6), for

$$C_d \approx 0.05 \quad (17)$$

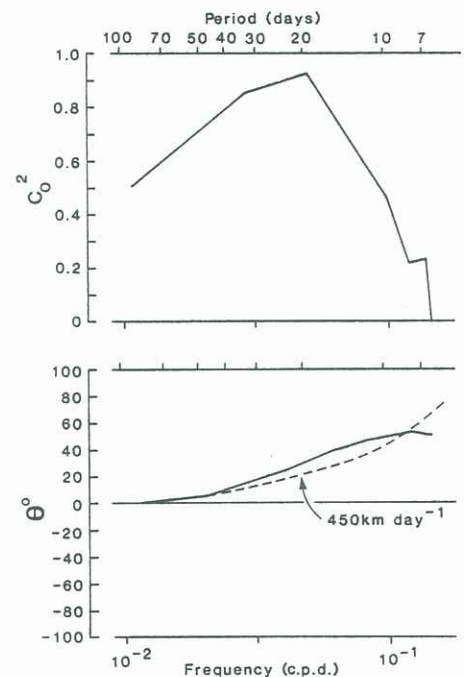


Fig. 5: Square coherence and phase between low-frequency sea level at Townsville and Carter Reef.

4 DISCUSSION

From eqs. (10), (16) and (17), it is clear that the value of C_d is one order of magnitude higher in the northern than in the central region. This difference results in a different response of the two regions to the wind forcing, and is due to the greater energy dissipation by the secondary circulation around islands and reefs in the densely reef-studded northern region than in the fairly reef-free central region.

5 ACKNOWLEDGEMENTS

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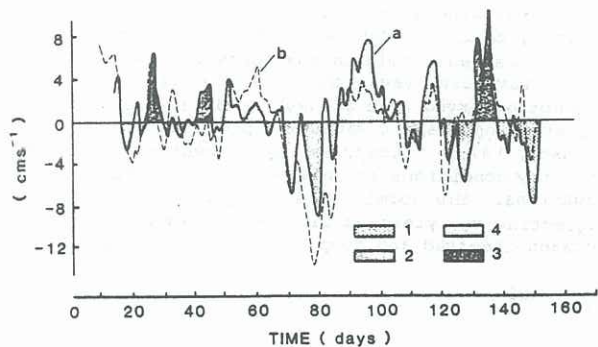


Fig. 6: Observed (a) and computed (b) longshore currents. The 4 shading codes will be explained in slides.

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